# Package: segMGarch (via r-universe)

September 8, 2024

Type Package
Title Multiple Change-Point Detection for High-Dimensional GARCH Processes
Version 1.2
Date 2018-12-10
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<b>Description</b> Implements a segmentation algorithm for multiple change-point detection in high-dimensional GARCH processes. It simultaneously segments GARCH processes by identifying 'common' change-points, each of which can be shared by a subset or all of the component time series as a change-point in their within-series and/or cross-sectional correlation structure.
License GPL (>= 2)
<b>Imports</b> Rcpp (>= 0.12.12), foreach, iterators, doParallel, fGarch, corpcor, mvtnorm, methods
Suggests MASS
LinkingTo Rcpp,RcppArmadillo
RoxygenNote 6.1.1
Encoding UTF-8
NeedsCompilation yes
Date/Publication 2019-01-17 22:30:03 UTC
Repository https://kakoko1984.r-universe.dev
RemoteUrl https://github.com/cran/segMGarch
RemoteRef HEAD

**RemoteSha** 83a6b58993d43cb0b78af034f2f3be515baf8a95

## Contents

segMGarch-package	2
DQtest	3
garch.seg-class	4
gen_pc_coef-class	5
kupiec	6
pc_cccsim-class	7
pc_Sigma	8
simMGarch-class	9
TL	10
tvMGarch-class	11
	12

## Index

segMGarch-package

Multiple Change-Point Detection for High-Dimensional GARCH Processes

## Description

Implements a segmentation algorithm for multiple change-point detection in high-dimensional GARCH processes described in Cho and Korkas (2018) ("High-dimensional GARCH process segmentation with an application to Value-at-Risk." arXiv preprint arXiv:1706.01155). It simultaneously segments GARCH processes by identifying 'common' change-points, each of which can be shared by a subset or all of the component time series as a change-point in their within-series and/or cross-sectional correlation structure. We adopt the Double CUSUM Binary Segmentation procedure Cho (2016), which achieves consistency in estimating both the total number and locations of the multiple change-points while permitting within-series and cross-sectional correlations, for simultaneous segmentation of the panel data of transformed time series.

It also provides additional functions and methods that relate to risk management measures and backtests.

## Details

We develop a segmentation algorithm for multiple change-point detection in high-dimensional GARCH processes. It simultaneously segments GARCH processes by identifying 'common' change-points, each of which can be shared by a subset or all of the component time series as a change-point in their within-series and/or cross-sectional correlation structure. The methodology first transforms the *d*-dimensional time series into d(d+1)/2-dimensional panel data consisting of empirical residual series and their cross-products, whereby change-points in the complex ((un)conditional variance and covariance) structure are made detectable as change-points in the simpler (mean) structure of the panel data at the price of the increased dimensionality. The main routine is garch.seg.

## Author(s)

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## DQtest

#### References

Cho, Haeran, and Karolos Korkas. "High-dimensional GARCH process segmentation with an application to Value-at-Risk." arXiv preprint arXiv:1706.01155 (2018).

Cho, Haeran. "Change-point detection in panel data via double CUSUM statistic." Electronic Journal of Statistics 10, no. 2 (2016): 2000-2038.

#### Examples

```
## Not run:
#pw.CCC.obj <- new("simMGarch")
#pw.CCC.obj <- pc_cccsim(pw.CCC.obj)
#pw.CCC.obj@d=10
#pw.CCC.obj@n=1000
#pw.CCC.obj@changepoints=c(250,750)
#pw.CCC.obj <- pc_cccsim(pw.CCC.obj)
#dcs.obj=garch.seg(pw.CCC.obj@y)
#dcs.obj$est.cps
#ts.plot(t(pw.CCC.obj@y),col="grey");grid()
#abline(v=dcs.obj$est.cps,col="red" )
#abline(v=pw.CCC.obj@changepoints,col="blue" )
#legend("bottom", legend=c("Estimated change-points", "Real change-points"),
#col=c("red", "blue"), lty=1:2, cex=0.8)
```

## End(Not run)

DQtest

A regression-based test to backtest VaR models proposed by Engle and Manganelli (2004)

## Description

Typical VaR tests cannot control for the dependence of violations, i.e., violations may cluster while the overall (unconditional) average of violations is not significantly different from  $\alpha = 1 - VaR$ . The conditional expectation should also be zero meaning that  $Hit_t(\alpha)$  is uncorrelated with its own past and other lagged variables (such as  $r_t$ ,  $r_t^2$  or the one-step ahead forecast VaR). To test this assumption, the dynamic conditional quantile (DQ) test is used which involves the following statistic  $DQ = Hit^T X (X^T X)^{-1} X^T Hit / \alpha (1 - \alpha)$  where X is the matrix of explanatory variables (e.g., raw and squared past returns) and Hit the vector collecting  $Hit_t(\alpha)$ . Under the null hypothesis, Engle and Manganelli (2004) show that the proposed statistic DQ follows a  $\chi_q^2$  where q = rank(X).

## Usage

```
DQtest(y, VaR, VaR_level, lag = 1, lag_hit = 1, lag_var = 1)
## S4 method for signature 'ANY'
DQtest(y, VaR, VaR_level, lag = 1, lag_hit = 1,
    lag_var = 1)
```

## Arguments

У	The time series to apply a VaR model (a single asset rerurn or portfolio return).
VaR	The forecast VaR.
VaR_level	The VaR level, typically 95% or 99%.
lag	The chosen lag for y.Default is 1.
lag_hit	The chosen lag for hit. Default is 1.
lag_var	The chosen lag for VaR forecasts. Default is 1.

## References

Engle, Robert F., and Simone Manganelli. "CAViaR: Conditional autoregressive value at risk by regression quantiles." Journal of Business & Economic Statistics 22, no. 4 (2004): 367-381.

#### Examples

```
#VaR_level=0.95
#y=rnorm(1000,0,4)
#VaR=rep(quantile(y,1-VaR_level),length(y))
#y[c(17,18,19,20,100,101,102,103,104)]=-8
#lag=5
#DQtest(y,VaR,VaR_level,lag)
```

garch.seg-class An S4 method to detect the change-points in a high-dimensional GARCH process.

## Description

An S4 method to detect the change-points in a high-dimensional GARCH process using the DCBS methodology described in Cho and Korkas (2018). If a tvMGarch is specified then it returns a tvMGarch object is returned. Otherwise a list of features is returned.

#### Usage

```
garch.seg(object, x, p = 1, q = 0, f = NULL, sig.level = 0.05,
Bsim = 200, off.diag = TRUE, dw = NULL, do.pp = TRUE,
do.parallel = 4)
## S4 method for signature 'ANY'
garch.seg(object = NULL, x, p = 1, q = 0, f = NULL,
sig.level = 0.05, Bsim = 200, off.diag = TRUE, dw = NULL,
do.pp = TRUE, do.parallel = 4)
## S4 method for signature 'tvMGarch'
garch.seg(object, p = 1, q = 0, f = NULL,
sig.level = 0.05, Bsim = 200, off.diag = TRUE, dw = NULL,
do.pp = TRUE, do.parallel = 4)
```

## Arguments

object	A tvMGarch object. Not necessary if x is used.
х	Input data matrix, with each row representing the component time series.
р	Choose the ARCH order. Default is 1.
q	Choose the GARCH order. Default is 0.
f	The dampening factor. If NULL then f is selected automatically. Default is NULL.
sig.level	Indicates the quantile of bootstrap test statistics to be used for threshold selec- tion. Default is 0.05.
Bsim	Number of bootstrap samples for threshold selection. Default is 200.
off.diag	If TRUE allows to look at the cross-sectional correlation structure.
dw	The length of boundaries to be trimmed off.
do.pp	Allows further post processing of the estimated change-points to reduce the risk of undersegmentation.
do.parallel	Number of copies of R running in parallel, if do.parallel = $0$ , %do% operator is used, see also foreach.

## References

Cho, Haeran, and Karolos Korkas. "High-dimensional GARCH process segmentation with an application to Value-at-Risk." arXiv preprint arXiv:1706.01155 (2018).

## Examples

```
#pw.CCC.obj <- new("simMGarch")
#pw.CCC.obj@d=10
#pw.CCC.obj@n=1000
#pw.CCC.obj@changepoints=c(250,750)
#pw.CCC.obj <- pc_cccsim(pw.CCC.obj)
#dcs.obj=garch.seg(x=empirObj@y,do.parallel = 4)</pre>
```

gen\_pc\_coef-class A method to generate piecewise constant coefficients

## Description

An auxilliary method to calculate piecewise constant coefficients for a user-specified vector of coefficients. The change-points are controlled by the changepoints slot in the simMGarch object.

#### Usage

```
gen_pc_coef(object, coef)
## S4 method for signature 'simMGarch'
gen_pc_coef(object, coef)
```

kupiec

#### Arguments

object	A simMGarch object.
coef	A vector of coefficients.

## References

Cho, Haeran, and Karolos Korkas. "High-dimensional GARCH process segmentation with an application to Value-at-Risk." arXiv preprint arXiv:1706.01155 (2018).

#### Examples

```
pw.CCC.obj <- new("simMGarch")
coef.vector <- gen_pc_coef(pw.CCC.obj,c(0.2,0.4))
ts.plot(coef.vector,main="piecewise constant coefficients",ylab="coefficient",xlab="time")</pre>
```

kupiec

Method to backtest VaR violation using the Kupiec statistics

#### Description

An S4 method that performs backtest for VaR models using the Kupiec statistics. For a sample of n observations, the Kupiec test statistics takes the form of likelihood ratio

$$LR_{PoF} = -2\log\left(\frac{(1-\alpha)^{T-n_f}\alpha^{n_f}}{\left(1-\frac{n_f}{T}\right)^{T-n_f}\left(\frac{n_f}{T}\right)^{n_f}}\right)$$
$$LR_{TFF} = -2\log\left(\frac{\alpha(1-\alpha)^{t_f-1}}{\left(\frac{1}{t_f}\right)\left(1-\frac{1}{t_f}\right)^{t_f-1}}\right),$$

where  $n_f$  denotes the number of failures occurred and  $t_f$  the number of days until the first failure within the *n* observations. Under  $H_0$ , both  $LR_{PoF}$  and  $LR_{TFF}$  are asymptotically  $\chi_1^2$ -distributed, and their exceedance of the critical value implies that the VaR model is inadequate.

## Usage

```
kupiec(y, VaR, VaR_level, verbose = TRUE, test = "PoF")
## S4 method for signature 'ANY'
kupiec(y, VaR, VaR_level, verbose = TRUE, test = "PoF")
```

## Arguments

У	The time series to apply a VaR model (a single asset rerurn or portfolio return).
VaR	The forecast VaR.
VaR_level	The VaR level, typically 95% or 99%.
verbose	If TRUE show the outcome. Default is TRUE.
test	Choose between PoF or TFF. Default is PoF.

## pc\_cccsim-class

#### References

Kupiec, P. "Techniques for Verifying the Accuracy of Risk Management Models." Journal of Derivatives. Vol. 3, 1995, pp. 73–84.

## Examples

```
pw.CCC.obj = new("simMGarch")
pw.CCC.obj@d = 10
pw.CCC.obj@n = 1000
pw.CCC.obj@changepoints = c(250,750)
pw.CCC.obj = pc_cccsim(pw.CCC.obj)
y_out_of_sample = t(pw.CCC.obj@y[,900:1000])
w=rep(1/pw.CCC.obj@d,pw.CCC.obj@d) #an equally weighted portfolio
#VaR = quantile(t(pw.CCC.obj@y[,1:899])%*%w,0.05)
#ts.plot(y_out_of_sample%*%w,ylab="portfolio return");abline(h=VaR,col="red")
#kupiec(y_out_of_sample%*%w,rep(VaR,100),.95,verbose=TRUE,test="PoF")
```

oc_cccsim-class	A method to simulate nonsta	ationary high-dimensional CCC (	GARCH
	models.		

#### Description

р

A S4 method that takes as an input a simMGarch object and outputs a simulated nonstationary CCC model. The formulation of the of the piecewise constant CCC model is given in the simMGarch class.

## Usage

```
pc_cccsim(object)
```

## S4 method for signature 'simMGarch'
pc\_cccsim(object)

## Arguments

object a simMGarch object

## References

Cho, Haeran, and Karolos Korkas. "High-dimensional GARCH process segmentation with an application to Value-at-Risk." arXiv preprint arXiv:1706.01155 (2018).

```
pw.CCC.obj <- new("simMGarch")
pw.CCC.obj <- pc_cccsim(pw.CCC.obj)
par(mfrow=c(1,2))
ts.plot(pw.CCC.obj@y[1,],main="a single simulated time series",ylab="series")
ts.plot(pw.CCC.obj@h[1,],main="a single simulated conditional variance",ylab="variance")</pre>
```

pc\_Sigma

## Description

An S4 method that takes a simMGarch object and outputs simulated correlated time series with a piecewise constant covariance matrix. The correlations are generated as  $\sigma_{i,i'} = \rho^{|i-i'|}$  with  $\rho$  taking values from (-1, 1). The exact variables that will contain a change-point are randomly selected and controlled by r in the simMGarch object.

## Usage

pc\_Sigma(object)

## S4 method for signature 'simMGarch'
pc\_Sigma(object)

## Arguments

object A simMGarch object.

#### References

Cho, Haeran, and Karolos Korkas. "High-dimensional GARCH process segmentation with an application to Value-at-Risk." arXiv preprint arXiv:1706.01155 (2017).

```
cp=500
n=2000
pw.CCC.obj <- new("simMGarch")
pw.CCC.obj@changepoints=cp
pw.CCC.obj@n=n
pc_Sigma.obj <- pc_Sigma(pw.CCC.obj)
par(mfrow=c(1,2))
#requires corrplot library
#correlation matrix before the changepoint
#corrplot::corrplot.mixed(cor(pc_Sigma.obj@cor_errors[1:cp,]), order="hclust", tl.col="black")
#correlation matrix after the changepoint
#corrplot::corrplot.mixed(cor(pc_Sigma.obj@cor_errors[(cp+1):n,]), order="hclust", tl.col="black")
```

simMGarch-class

## Description

A specification class to create an object of a simulated piecewise constant conditional correlation (CCC) model denoted by  $r_t = (r_{1,t}, \ldots, r_{n,t})^T$ ,  $t = 1, \ldots, n$  with  $r_{i,t} = \sqrt{h_{i,t}}\epsilon_{i,t}$  where  $h_{i,t} = \omega_i(t) + \sum_{j=1}^p \alpha_{i,j}(t)r_{i,t-j}^2 + \sum_{k=1}^q \beta_{i,k}(t)h_{i,t-k}$ . In this package, we assume a piecewise constant CCC with p = q = 1.

## Slots

y The  $n \times d$  time series.

cor\_errors The  $n \times d$  matrix of the errors.

- h The  $n \times d$  matrix of the time-varying variances.
- n Size of the time series.
- d The number of variables (assets).
- r A sparsity parameter to conrol the impact of changepoint across the series.

multp A parameter to control the covariance of errors.

changepoints The vector with the location of the changepoints.

- pw A logical parameter to allow for changepoints in the error covariance matrix.
- a0 The vector of the parameters a0 in the individual GARCH processes denoted by  $\omega_i(t)$  in the above formula.
- al The vector of the parameters al in the individual GARCH processes denoted by  $\alpha_i(t)$  in the above formula.
- b1 The vector of the parameters b1 in the individual GARCH processes denoted by  $\beta_i(t)$  in the above formula.
- BurnIn The size of the burn-in sample. Note that this only applies at the first simulated segment. Default is 50.

#### References

Cho, Haeran, and Karolos Korkas. "High-dimensional GARCH process segmentation with an application to Value-at-Risk." arXiv preprint arXiv:1706.01155 (2017).

```
pw.CCC.obj <- new("simMGarch")
pw.CCC.obj <- pc_cccsim(pw.CCC.obj)
par(mfrow=c(2,2))
ts.plot(pw.CCC.obj@y[1,]);ts.plot(pw.CCC.obj@y[2,])
ts.plot(pw.CCC.obj@h[1,]);ts.plot(pw.CCC.obj@h[1,])</pre>
```

Method to backtest VaR violation using the Traffic Light (TL) approach of Basel

## Description

A method that performs backtest for VaR models using the TL approach. According to Basel, a VaR model is deemed valid if the cumulative probability of observing up to  $n_f$  failures is less than 0.95 (green zone) under the binomial distribution with n (sample size) and Var level as the parameters. If the cumulative probability is between 0.95 and 0.9999 a VaR model is in yellow zone. Otherwise (>0.9999) a VaR model is in red zone.

## Usage

TL(y, n = NULL, no\_fail = NULL, VaR, VaR\_level)
## S4 method for signature 'ANY'
TL(y, n = NULL, no\_fail = NULL, VaR, VaR\_level)

#### Arguments

У	The time series to apply a VaR model (a single asset rerurn or portfolio return).
n	If y is not provided, then insert sample size. Default is NULL.
no_fail	If y is not provided, then insert number of fails. Default is NULL.
VaR	The forecast VaR.
VaR_level	The VaR level, typically 95% or 99%.

#### References

Basle Committee on Banking Supervision (1996). "Supervisory Framework for the Use of 'Back-testing' in Conjunction with the Internal Models Approach to Market Risk Capital Requirements".

## Examples

```
pw.CCC.obj = new("simMGarch")
pw.CCC.obj@d = 10
pw.CCC.obj@n = 1000
pw.CCC.obj@changepoints = c(250,750)
pw.CCC.obj = pc_cccsim(pw.CCC.obj)
y_out_of_sample = t(pw.CCC.obj@y[,900:1000])
w=rep(1/pw.CCC.obj@d,pw.CCC.obj@d) #an equally weighted portfolio
#VaR = quantile(t(pw.CCC.obj@y[,1:899])%*%w,0.05)
#ts.plot(y_out_of_sample%*%w,ylab="portfolio return");abline(h=VaR,col="red")
#TL(y=y_out_of_sample%*%w,VaR=rep(VaR,100),VaR_level = 0.95)
```

ΤL

tvMGarch-class

## Description

A specification class to create an object of a nonstationary multivariate class model reserved for real (empirical) applications. It inherits from simMGarch.

## Slots

out\_of\_sample\_prop Proportion of y to keep for out-of-sample forecasting expressed in %.

out\_of\_sample\_y The out of sample y matrix reserved for forecasting and backtesting exercises.

in\_sample\_y The in-sample y matrix reserved for estimation (calibration) and change-point detection.

## References

Cho, Haeran, and Karolos Korkas. "High-dimensional GARCH process segmentation with an application to Value-at-Risk." arXiv preprint arXiv:1706.01155 (2018).

```
simObj <- new("simMGarch")
simObj@d <- 10
simObj@changepoints <- c(250,750)
simObj <- pc_cccsim(simObj)
empirObj <- new("tvMGarch") #simulated, but treated as a real dataset for illustration
empirObj@y <- simObj@y
empirObj@out_of_sample_prop <- 0.1
#empirObj=garch.seg(object=empirObj,do.parallel = 4)##Not run</pre>
```

## Index

 \* Double CUSUM Binary Segmentation, high dimensionality, nonstationarity segMGarch-package, 2
 \* multiple change-point detection, multivariate GARCH, stress period selection, segMGarch-package, 2

DQtest, 3 DQtest, ANY-method (DQtest), 3 DQtest-class (DQtest), 3 DQtest-methods (DQtest), 3

for each, 5

kupiec, 6
kupiec, ANY-method (kupiec), 6
kupiec-class (kupiec), 6
kupiec-methods (kupiec), 6

pc\_Sigma,simMGarch-method(pc\_Sigma), 8
pc\_Sigma-class(pc\_Sigma), 8
pc\_Sigma-methods(pc\_Sigma), 8

segMGarch(segMGarch-package), 2
segMGarch-package, 2
simMGarch-class, 9

## TL, 10

TL, ANY-method (TL), 10 TL-class (TL), 10 TL-methods (TL), 10 tvMGarch-class, 11